

# Reece D. Huff

COMPUTER VISION · MACHINE LEARNING · OPTIMIZATION

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## Summary

I am an Electrical Engineering and Computer Science Ph.D. student with a passion for open-source software development. My drive lies in harnessing the power of parallel computing and deep learning to synergize medical imaging techniques, such as ultrasound, with motion capture systems in order to unravel the underlying mechanisms contributing to musculoskeletal disorders. My expertise in handling large, noisy datasets allow me to effectively develop innovative solutions for complex biomedical challenges.

## Education

### University of California, Berkeley

Berkeley, CA

PH.D. IN ELECTRICAL ENGINEERING AND COMPUTER SCIENCE

May 2023 - May 2027

- Advisor: Preeya Khanna
- Major: Machine Learning, Minors: Computer Vision & Statistics
- Awards: NSF GRFP, Graduate Division Block Grant

### University of California, Berkeley

Berkeley, CA

M.S. IN MECHANICAL ENGINEERING (GPA: 3.97/4.00)

Aug. 2021 - May 2023

- Major: Biomechanical Engineering, Minors: Computer Science & Statistics
- Thesis: *Deep learning enables accurate soft tissue deformation estimation in vivo*

### Boston University

Boston, MA

B.S. IN BIOMEDICAL ENGINEERING (GPA: 3.99/4.00)

Aug. 2018 - May 2021

- Advisors: Elise Morgan & Paul Barbone
- Awards: Goldwater Scholarship, Distinguished Summer Research Fellowship

## Skills

<b>Programming</b>	C/C++ · Rust · Python · Julia · HTML+CSS · SQL · Bash · LaTeX · Git · Metal · Swift · MATLAB · Mathematica
<b>Software</b>	PyTorch · TensorFlow · Tensorboard · CUDA · CVXPY · pandas · sklearn · OpenMP · MPI · OpenCL · OpenGL
<b>Techniques</b>	parallel computing · deep learning · computer vision · markerless motion capture · finite element modeling
<b>General</b>	Google Suite · Adobe Creative Cloud · Microsoft Office

## Publications

2023	<b>Deep learning enables accurate <i>in vivo</i> deformation prediction</b> , in preparation	<a href="#">code</a> · <a href="#">project page</a>
2023	<b>Relating <i>in vivo</i> strain of the FDS tendon with grip force</b> , Proc. Hum. Factors Ergon. Soc.	<a href="#">paper</a> · <a href="#">project page</a>
2022	<b>Comparing intervertebral disc geometry measurement method</b> , JOR Spine	<a href="#">paper</a> · <a href="#">project page</a>
2022	<b>Finite-element modeling of lumbar disc herniation</b> , JBME	<a href="#">paper</a> · <a href="#">project page</a>

## Experience

### University of California, Berkeley

Berkeley, CA

GRADUATE RESEARCH ASSISTANT

Aug. 2021 - present

- Designed a custom printed circuit board for a inertial measurement unit system
- Developed a novel deep-learning approach for measuring *in vivo* tissue deformation
- Physics-based and statistical modeling of muscle- and torque-driven flexion to the intervertebral disc

### Boston University

Boston, MA

UNDERGRADUATE RESEARCH ASSISTANT

Mar. 2019 - Aug. 2021

- Optimized bone tracking algorithm that measures the displacement field in a fracturing vertebra

## Coursework

<b>Computational</b>	Machine Learning, Deep Learning, Computer Vision and Computational Photography, Parallel Computing, Deep Reinforcement Learning, Computational Linear Algebra, Computational Numerical Methods, Convex Optimization
<b>Mechanics</b>	Orthopedic Biomechanics, Biomaterials, Finite Element Modeling, Continuum Mechanics, Elasticity, Fluid Mechanics, Thermodynamics, Statics, Dynamics, Statistical Mechanics
<b>Mathematics</b>	Applied Mathematics, Linear Algebra, Probability, Statistics, Advanced Calculus, Differential Equations
<b>General</b>	Physics, Chemistry, Molecular Biology, Engineering Design, Circuits, Physiology